



account their homogeneity. This allows to treat bits of similar pixels equivalently, but not the bits of pixels of different homogeneity level. We focus in this paper in binary codes although any q-ary code can be used with the same techniques.

We use the following notations:

m: the (secret) message,

x: the cover,

y: the modified cover,

E(): the embedding map,

R(): the retrieval map.

This paper is organized as follows. Section 2 describes how classical linear error correcting codes are applied in steganography. In Section 3 we introduce Linear error-block codes and recall the main tools to be used. Section 4 is our main contribution, it presents our steganographic scheme and motivates the use of Linear Error-Block Codes. The experimental results are given in Section 5.

Section 6 involves conclusion and perspective of this work.

## 2 The F5 algorithm

In 1998, Crandall was the first one to bring the idea of using error correcting codes in steganography [1]. Three years later, Westfeld designed a steganographic algorithm, called F5, that uses this idea [2]. Our proposal is a generalization of this algorithm to linear error block codes. Here is an overview of the F5 algorithm.

Let C be a linear error correcting code of parity check matrix H. The retrieval map requires simply computing the syndrome of the modified cover  $R(y) := S(y) = Hy^T$ .

The embedding algorithm consists of three steps. First compute  $u := S(x) - m$ , then find  $e_u$  a word of smallest weight among all words of syndrome u. This is

the syndrome decoding problem. It is equivalent to decode u in C and get the error vector  $e_u$ . Finally compute  $E(m; x) := x - e_u$ .

For verification we have

$$R(E(m, x)) = S(x - e_u) = S(x) - S(e_u) = S(x) - u = m. \quad (1)$$

## Linear Error-Block Codes in Steganography 3

### 3 Linear error-block codes

Linear error-block codes (LEBC) are a generalization of linear error correcting codes. They were introduced in [3], and studied in several works [4{7]. The authors of [3] defined a special Hamming bound for LEBC with minimum distance even. The codes attaining this bound are thus considered perfect. There exist larger families of perfect linear error-block codes than the classical linear error correcting codes, but all of the known families are of minimum distance either 3 or 4 (in addition to the well known classical perfect codes which are also perfect error-block codes) [5]. The existence of more perfect LEBC is still an open problem. In this section, we first recall preliminary notions to be used. Then we describe linear error-block codes. We discuss the metric used to deal with these codes.

A composition  $\pi$  of a positive integer n is given by  $n = l_1 m_1 + l_2 m_2 + \dots + l_r m_r$ , where  $r, l_1, l_2, \dots, l_r, m_1, m_2, \dots, m_r$  are integers  $\geq 1$ , and is denoted  $\pi = [m_1]^{l_1} [m_2]^{l_2} \dots [m_r]^{l_r}$  (2)

If moreover  $m_1 > m_2 > \dots > m_r \geq 1$  then  $\pi$  is called a partition.

Let q be a prime power and  $F_q$  be the finite field with q elements. Let  $s, r, l_1, l_2, \dots, l_r, n_1, n_2, \dots, n_s$  be the non negative integers given by a partition  $\pi$  as

$$s = l_1 + \dots + l_r; \\ n_1 = n_2 = \dots = n_{l_1} = m_1$$

$$n_{11}+1 = n_{11}+2 = \dots = n_{11}+l_2 = m_2$$

$$\dots$$

$$\dots$$

$$n_{11}+\dots+l_{r-1}+1 = n_{11}+\dots+l_{r-1}+2 = \dots$$

$$= n_s = m_r$$

We can write

$$\pi = [n_1][n_2] \dots [n_s]: (3)$$

Let  $V_i = F_q^{n_i}$  ( $1 \leq i \leq s$ ) and  $v = v_1 \oplus v_2 \oplus \dots \oplus v_s \in F_q^n$ . Each vector in  $V$  can be written uniquely as  $v = (v_1, \dots, v_s)$ ,  $v_i \in V_i$  ( $1 \leq i \leq s$ ). For any  $u = (u_1, \dots, u_s)$  and  $v = (v_1, \dots, v_s)$  in  $V$ , the  $\pi$ -weight  $w_\pi(u)$  of  $u$  and the  $\pi$ -distance  $d_\pi(u, v)$  of  $u$  and  $v$  are defined by

$$w_\pi(u) = \#\{i/1 \leq i \leq s, u_i \neq 0 \in V_i\} \text{ and} (4)$$

$$d_\pi(u, v) = w_\pi(u - v) = \#\{i/1 \leq i \leq s, u_i \neq v_i\}. (5)$$

This means that a fixed vector can be of different  $\pi$ -weights if we change  $\pi$ . For example, consider the word  $v = 1010001101$  of length 10 and the two partitions of the number 10:  $\pi = [3][2]^3[1]$  and  $\pi' = [3]^2[2][1]^2$ . We have  $w_\pi(v) = 4$  while

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$$w_{\pi'}(v) = 3.$$

An  $F_q$ -linear subspace  $C$  of  $V$  is called an  $[n, k, d]_q$  linear error-block code over  $F_q$  of type  $\pi$ , where  $k = \dim_{F_q}(C)$  and  $d = d_\pi(C)$  is the minimum  $\pi$ -distance of  $C$ , which is defined as  $d = \min\{d_\pi(c, c')/c, c' \in C; c \neq c'\}$   $= \min\{w_\pi(c)/0 \neq c \in C\}$ :

(6)

Remark 1. A classical linear error correcting code is a linear error-block code of type  $\pi = [1]^n$ .

Remark 2. A linear error-block code with a composition type is equivalent to some linear error-block code with a partition type.

The difference between decoding linear error block codes and decoding classi-

cal linear error correcting codes is the use of the  $\pi$ -distance instead of the Hamming distance. Therefore, coset leaders are words having minimum  $\pi$ -weight, although sometimes they are not of minimum Hamming weight.

It is well known that perfect codes have odd minimum distance. Nonetheless, the Hamming bound presented in [3] allows to construct perfect codes with even minimum distance. This is done by considering the sets

$$B'_\pi(c, d/2) = b_\pi(c, d/2 - 1) \sqcup \{x \in V; d_\pi(x, c) = d/2 \text{ and } x_1 \neq c_1\}$$

(7)

where  $B_\pi(c, r) = \{x \in V; d_\pi(x, c) \leq r\}$  is the ball of center a codeword  $c$  and radius  $r$ . The sets  $B'_\pi(d/2)$  are pairwise disjoint. (And if the code is perfect, their union for all codewords  $c$  covers the space  $V$ ). A word  $x \in V$  is thus decoded as  $c$  if  $x \in B'_\pi(c, d/2)$ . Therefore, the decoding algorithm of a code with even minimum distance  $d$  corrects, further, error patterns with both  $\pi$ -weight  $d/2$  and non null first block.

To construct a syndrome table, we add the following condition. If a coset of weight  $d/2$  has more than one leader, we select among them a word which has a non null first block. Note that the coset leader has not to be unique unless the code is perfect. The maximum likelihood decoding (MLD) [8] is slightly modified. Remark 3. This decoding technique can also be used with classical codes. Therefore, quasi-perfect codes [8] are considered perfect and can perform complete decoding. This makes them more efficient in steganography.

Example 1. Let  $\pi = [3][2]^2[1]$ , if we have to choose a coset leader between the words  $e_1 = 000|01|00|1$  and  $e_2 = 010|01|00|0$ , we select the second one, since

they are both of  $\pi$ -weight 2 and the first block of  $e_2$  is not null.

Note that this does not guaranty that every error pattern of  $\pi$ -weight  $d/2$  can be corrected. We present below an example of syndrome decoding of a given linear error-block code.

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Example 2. Consider C the binary [7, 3] code of type  $\pi = [3][2][1]^2$ , defined with its parity check matrix

$$H = \begin{pmatrix} 1 & 1 & 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 & 0 \end{pmatrix}$$

Syndromes are computed by the classical formula  $s = Hx^T$ ,  $x \in F_2^7$ .

The words which have the same syndrome belong to the same coset.

Coset leaders are words which have the minimum  $\pi$ -weight in their cosets. The syndrome table of the code C is presented in Table 1. We added two columns to mark, in the

\_rst one, the di\_erence between the use of the  $\pi$ -distance and the Hamming distance, and in the second one, cases where  $\pi$ -metric decoding is not unique (since  $d_\pi = 2$ , correction capacity is  $t_\pi = 1$ ). Note that in line 5, since the first

block of the right side column word is null, it can not be chosen as a coset leader. In lines 6 and 8, the third column words have  $\pi$ -weight 2, they also can not be coset leaders. While in the last four lines, all of the right side column words can be a coset leader.

Table 1. Syndrome table of the error-block code C.

### 4 Linear error-block codes in steganography

By using the  $\pi$ -distance, when we correct a single error-block, all the bits in the block are being corrected at once [6], which means that we recover within one error correction not less than one message bit. The maximum recovered bits is

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 the size of the corrected block. In other words, assume that to embed a  $k$ -bit message we have to modify  $r$  bits in the  $n$ -bit cover. These  $r$  bits are located in  $r$  blocks where  $r \leq r$ . Thus we have to provoke  $r$  errors, whilst with a classical code we provoke  $r$  errors.

However, it may happen, for some partitions, that alteration of a whole block is needed, while if we use a classical code we just need to ip a single bit to embed the same message. For instance, in Example 3 (Page 8), the coset leader for Hamming distance is  $e_u = 0001000$  (Line 5 of Table 1), which looks more interesting to use. Nevertheless, the blocks are taken from di\_erent areas of the cover in order to give preferential treatment to each block of bits. The size and

the order of the blocks are considered as well. It is clear that the smaller is the block, the less is its probability of distortion. We show in the next subsection that it might be more suitable to use a whole block rather than a single bit. Although syndrome decoding using the  $\pi$ -distance returns coset leaders with more non null bits than Hamming distance, application of linear error-block codes in steganography is motivated by the following vision. In general, pictures feature areas that can better hide distortion than other areas. The human vision system is unable to detect changes in inhomogeneous areas of a digital media, due to the complexity of such areas. For example, if we modify the gray values of pixels in smooth areas of a gray-scale image, they will be more easily noticed by human eyes. In the other hand, the pixels in edged areas may tolerate larger changes of pixel values without causing noticeable changes (Fig. 1). So, we can keep the changes in the modified image unnoticeable by embedding more data in edged areas than in smooth areas.



Fig. 1. Embedding 16-valued pixels in two areas of Lena gray-scale image. Another vision consists of using one or two bits next to the least significant ones. Actually, the least significant bits (LSB) are the most suitable, but

we can use further bit levels if this does not cause noticeable change to the image (Fig. 2). There are many embedding methods that use bit significance levels in different ways [10–13]. For our method, there are two possibilities. First one, we select a list  $(p_i)_{i \in I}$  of pixels to be modified, and embed the message within (some) bit levels of this list. The pixels must then be located in a sufficiently inhomogeneous area. The second way is by selecting independently, for each bit level  $j$ , a list  $(p_i)_{i \in I_j}$  of pixels to be manipulated. Hence more bits are used, Linear Error-Block Codes in Steganography resulting in a larger cover size. If the pixels are strong enough against distortion, higher bit levels can be used but with smaller and smaller block sizes.

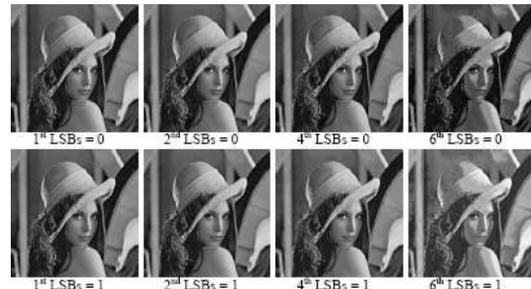


Fig. 2. Lena image with different bit levels switched to 0 or 1.

We sketch our method in Figure 3. The cover bits are assorted by their ability to hide distortion. Thus, in the previous examples, first level bits refer to the most inhomogeneous areas or to the least significant bits. We can also combine these methods by assorting bits starting from the LSB of the most inhomogeneous area to the last significant bit considered of the most homogeneous area.

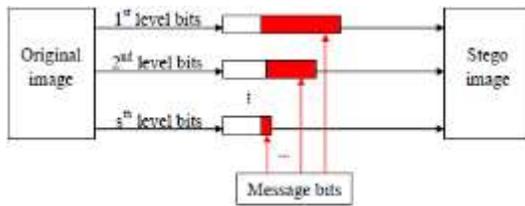


Fig.3. Overview of our embedding method.

Now assume we have made  $s$  sequences of cover bits assorted by their ability to support distortion in the decreasing sense (i.e. the first sequence bits are the less sensitive to distortion). We note the  $i^{\text{th}}$  sequence  $(a_{ij})_{j=1,2,\dots,m_i}$ . In the next step, we reorder the bits such that the cover will be written as blocks  $x = (x_1, x_2, \dots, x_s)$  where  $x_i \in V_i$  is a subsequence of  $n_i$  bits of  $\alpha_i$  (we use the notation of Section 3). Considering these blocks, a partition  $\pi = [n_1][n_2] \dots [n_s]$

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of the size of the cover is defined. And the cover is viewed as a list of vectors

$x \in V$ . Therefore, the distortion of the first level bits is more probable than the distortion of the second level bits, and so on. The sizes of the blocks are chosen such that the complete distortion of any block (the distortion of all of its bits) has an equal effect on the image change. In the next section we show how is a linear error-block code of type  $\pi$  used.

Remark 4. If the cover bits have equal influence on image quality, for example only LSBs are used or all the bits are located in an area of a constant homogeneity, then  $\pi$  turns to the classical partition  $\pi = [1]^n$ .

The steganographic protocol we propose follows the same steps as in Section 2. But with the  $\pi$ -distance, the syndrome decoding seeks coset leaders among vectors with non null first block. Therefore, we can have better image

quality since first blocks contain the less sensitive bits. In the following we describe the steps of the embedding/retrieval algorithm and give a practical example.

Let  $C$  be an  $[n, k]$  linear error-block code of type  $\pi$  and of parity check matrix  $H$ . The syndrome of a vector  $v \in V$  is computed by the product  $S(v) = Hv^T$ . Hence the retrieval algorithm is defined by  $R(y) := S(y) = Hy^T$ .

The first step of the embedding algorithm is also simple, it consists of computing  $u := S(x) - m$ .

Now to accomplish the embedding operation we compute  $E(m; x) := x - e_u$  where  $e_u$  is the coset leader of  $u$ . The vector  $e_u$  is also the error vector found by decoding  $u$  in  $C$ . We can compute it by the decoding algorithm presented in Section 3.

Remark 5. In our steganographic protocol, we do not need to perform unique decoding. We just choose a coset leader with the only condition that it has minimum  $\pi$ -weight in order to get the least modifications on the cover image.

The final step is computing  $y = x - e_u$ .  
 Example 3. Assume we have a (part of a) cover  $x = 0001101$ , and that the first block of three bits is located in an area that can hide more distortion than the second block of two bits, and that the remaining two blocks of one bit are more sensitive to distortion. The cover is of size 7 and we just defined the partition  $\pi = [3][2][1]^2$ . We use the code  $C$  of Example 2. Let  $m = 1100$  be the message to hide. We follow the steps:  
 Embedding

1.  $u = S(x) - m = 0110$

2.  $e_u = 1010000$  (found from the syndrome table)

3.  $y = E(x;m) = x - e_u = 1011101$

Retrieval

$$R(y) = S(y) = 1100$$

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## 5 Results

The proposed method was tested with 3 different messages to be hidden within the famous Lena gray-scale image of size  $256 \times 256$ . For each message, we applied several linear error-block codes with different partitions. The messages are divided to blocks which have the same size as the code length.

Table 2. Steganography performance of a [7,3] error-block code.

$[4]^2 [1]$	3	2	2.0000	0.6666
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$\pi$	s	$p_\pi$	$(n-k)/s$	$p_\pi/s$
$[1]^7$	7	2	0.5714	0.2857
$[2][1]^5$	6	2	0.6666	0.3333
$[2]^2[1]^3$	5	2	0.8000	0.4000
$[3][2][1]^2$	4	2	1.0000	0.5000
$[4][2][1]$	3	2	1.3333	0.6666

Table 3. Steganography performance of a [6,3] error-block code.

$\pi$	s	$p_\pi$	$(n-k)/s$	$p_\pi/s$
$[1]^6$	6	2	0.5000	0.3333
$[2][1]^4$	5	1	0.6000	0.2000
$[3][1]^3$	4	1	0.7500	0.2500
$[3][2][1]$	3	1	1.0000	0.3333
$[5][1]$	2	1	1.5000	0.5000

Table 4. Steganography performance of a [9,3] error-block code.

$\pi$	s	$p_\pi$	$(n-k)/s$	$p_\pi/s$
$[1]^9$	9	2	0.6666	0.2222
$[2]^2[1]^5$	7	2	0.8571	0.2857
$[3][2][1]^4$	6	2	1.0000	0.3333
$[3][2]^2[1]^2$	5	2	1.2000	0.4000

Tables 2, 3 and 4 summarize the results for one block embedding. In order to compare the performance of different partitions, we used the following parameters,  $(n-k)/s$  measures the block-embedding rate,  $p_\pi$  measures the maximum embeddable blocks, it is also the  $\pi$ -covering radius of the code defined by  $p_\pi = \max\{d_\pi(x, C), x \in F_q^n\}$ .

$$(8)$$

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And finally  $p_\pi/s$  measures the block embedding average distortion.

The results show that a careful selection of the code and the partition is critical. For a fixed code, a partition of a few number of blocks causes a big block-average distortion

$p_\pi/s$

(if the covering radius  $p_\pi$  remains unchanged), whilst a big number of blocks causes a small block-embedding rate  $(n-k)/s$ . For the [6, 3] code of Table 3, it is clear that the partition  $[2][1]^4$  is the best, since it provides the largest block-embedding capacity and the smallest block-embedding distortion.

## 6 Conclusion and perspective

The steganographic protocol we introduce in this paper allows to handle different cover bits using linear error block codes. The choice of the code is a very critical especially for covers with few first level bits. Experimental results show that there exist linear error block codes which provide high quality images and good security

parameters. The forthcoming work involves specifying the space of codes to use in order to automatically achieve acceptable quality and security objectives.

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